SPATIAL PLANNING & URBAN DESIGN

# Compatibility of Automated Vehicles in Street Spaces – An analysis from Vienna, Austria

Future Perspectives on Public Spaces

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## Overview





# Conclusion 4.

### Results

Volume at peak hour

# **1. Introduction**

- Most studies on impacts of Automated Vehicles (AVs) on travel behavior indicate an increase in traffic ulletvolume (vehicle miles travelled) due to AVs
- Studies were mostly conducted on city wide level  $\rightarrow$  no focus on changes within different street spaces ullet
- Streets spaces
  - subject to wide range of competing usage demands
  - not only traffic function but also places for people to move, stroll, meet, sit or play
  - needs between motor vehicles and other road users only reasonable until a certain limit, above this limit no longer compatible with needs of other road users
- How compatible are AVs in different street spaces due changes in traffic volume?

# **2. Method: Scenarios**

- Simulation of three different scenarios in MATSim
- Whole street network of Vienna, Austria



### **Scenarios**

### **Scenario 3**

Automation of all current private vehicles

+25% utility increase in MATSim +40% road capacity increase



# Assessment of Compatibility I

### 1) Determination of Maximum

### **Compatible Traffic Volume**

Maximum number of vehicles per

hour at peak hour

- Based on Area type and age of buildlings, zoning categories and number of shops and business
- Five different area categories



### • • • •

	<b>.</b> .	Compatible traffic volume (vehicles at peak			
	Area category	hour)			
		<= 20 (well compatible)			
		>20 - <b>50</b> (compatible)			
	City contro/ hucinoss district	>50 – 150 (only just compatible)			
	City tentre/ business district	>150 – 400 (not compatible)			
		>400 (completely not compatible)			
		<= 50 (well compatible)			
		>50 - <b>150</b> (compatible)			
	Mixed use with intensive commercial use	>150 – 400 (only just compatible)			
	wixed-use with intensive conintercial use	>400 – 600 (not compatible)			
		>600 (completely not compatible)			
		<= 150 (well compatible)			
		>150 - <b>400</b> (compatible)			
	Mixed use with medium intensive commercial use	>400 – 600 (only just compatible)			
	wixed-use with medium intensive commercial use	>600 – 1000 (not compatible)			
		>1000 (completely not compatible)			
		<= 400 (well compatible)			
		>400 - <b>600</b> (compatible)			
	Low dencity residential	>600 – 1000 (only just compatible)			
$\sim 2$	Low-density residential	>1000 – 1200 (not compatible)			
ζ		>1200 (completely not compatible)			
		<= 600 (well compatible)			
		>600 - <b>1000</b> (compatible)			
	Industrial	>1000 – 1200 (only just compatible)			
m		>1200 – 1500 (not compatible)			
		>1500 (completely not compatible)			

# **Assessment of Compatibility II**

2) Adaptation of the Maximum

**Compatible Traffic Volume based** 

on further characteristics

- Distribution of space •
- Use by pedestrians and cyclists
- Speed
- Heavy goods vehicle traffic •
- Crossing needs •
- Green and design elements ٠
- Crossability •

+ Weighting of Criteria

Distribution of space ratio between area width for pedestrians and cyclists in comparison to area width for motorized traffic



Speed average speed of motor vehicles in reference scenario



**Crossing needs** 



Use by pedestrians and cyclists



Heavy goods vehicle traffic share of heavy goods traffic of the total motor vehicle traffic volume



Green and design elements number of trees, bushes and design elements





### Weighting of Criteria

Criterion	Weighting 1: Equal Weights of Criteria	Weighting 2: Higher Weight for C1, Lower Weight for C5 and C6	Weighting 3: Considerable Higher Weight for C1, Lower Weights for C3 to C7			
C1: Distribution of space	1	2	3.5			
C2: Use by pedestrians and cyclists	1	1	1			
C3: Speed	1	1	0.5			
C4: Heavy-goods vehicle traffic	1	1	0.5			
C5: Crossing needs	1	0.5	0.5			
C6: Green and design elements	1	0.5	0.5			
C7: Crossability	1	1	0.5			

### Crossability



# **Assessment of Compatibility III**

3) Comparison between actual

traffic volume and adapted

maximum compatible traffic

volume

• For reference scenario and all

three scenarios with AVs

	Maximum Compatible Traffic Volume	Adaptation of Maximum Compatible Traffic Volume										
Street Section		C1	C2	C3	C4	C5	C6	C7	Total	Adapted Maximum Compatible Traffic Volume	Actual Traffic Volume	Assessment of Compatibility
Street section in area category	150	+175	-100	-25	-50	±0	-25	+50	+25	≤75 (++) >75 bis 175 (+) >175 bis 425 (o) >425 bis 625 (-) >625 ()	157	+ compatible
"mixed-use with intensive		weights										
commercial use"		3.5	1	0.5	0.5	0.5	0.5	0.5	_			
		unweighted										
		+50	-100	-50	-100	±0	-50	+100				

C1 = criterion distribution of space; C2 = criterion use by pedestrians and cyclists; C3 = criterion speed; C4 = criterion heavy-goods vehicle traffic; C5 = criterion crossing needs; C6 = criterion green and design elements; C7 = criterion crossability.

## **3. Results: Street-Level Changes in Traffic Volume at Peak Hour**

- Increase of vehicles at peak hour in the inner parts of the city for both scenarios with SAVs
- Decrease of vehicles at peak hour in outskirts, ٠ especially for Scenario 2
- Increase of vehicles at peak hour at higherlevel street network for private AVs





### Scenario 2 in comparison to reference scenario

Scenario 3 in comparison to reference scenario

### **Reference** scenario

## **Changes in the Compatibility of Street Spaces**

- Actual traffic volume in the reference scenario is mostly not compatible with the needs of the surrounding uses and users in the higher-level street network and in several streets in the lower-level street network in the inner parts of the city
- All scenarios with AVs show lower levels of • compatibility in comparison to the reference scenario, especially in the inner parts of the city
- Improvement in compatibility along streets in the



Scenario 2 in comparison to reference scenario



### Scenario 1 in comparison to reference scenario

Scenario 3 in comparison to reference scenario



## Changes in traffic volume in already not compatible street spaces in the reference scenario

- For scenarios with SAVs increases of vehicles at • peak hour in completely non-compatible street spaces are observable only in the eastern and southern part of Vienna
- In Scenario 3 traffic volume at peak hour highly • increases in most of the already completely noncompatible streets  $\rightarrow$  even higher noncompatibility and further increasing separating or barrier effect of such streets





### Scenario 2 in comparison to reference scenario

Scenario 3 in comparison to reference scenario

## 4. Conclusion

### Spatially different strategies for the implementation of AVs are needed in the future!

### Street spaces in areas in the outskirts

- Sensibility towards a further increase of vehicles due to AVs is lower and conflicts less with other needs of uses and users than in the inner parts of the city
- Implementing SAVs in addition to public transport may decrease traffic in these areas and thus might be interesting for cities to consider
- Street spaces in which the current traffic volume at peak hour is already not compatible with the usage demands and especially in innercity areas
  - AVs could induce traffic volumes
  - Street spaces should be designed to be more compatible with the needs of pedestrians and cyclists e.g., by implementing walking and cycling • infrastructure, speed reduction, or additional crossing aids or the implementation of AVs should be linked to these measures.
  - conversion of parking spaces in favor of such design elements and space for pedestrians and cyclists seems important and could become an appropriate and (more accepted) measure with regard to future concepts with AVs, as parking needs—especially in the case of SAVs – could be reduced
- Analyses that take into account the spatial heterogeneity in cities are important!  $\rightarrow$  not only with regard to compatibility but also with regard • to the technical-infrastructural suitability of street spaces for AVs (e.g. different complexity for automated driving systems)

## Further information

Soteropoulos, A., Berger, M., Mitteregger, M. (2021). Compatibility of Automated Vehicles in Street Spaces: Considerations for a Sustainable Implementation. Sustainability, 13(5), 2732. <u>https://www.mdpi.com/2071-1050/13/5/2732</u> •
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# Thank you!

Do you have any question?

Ask Aggelos Soteropoulos, aggelos.soteropoulos@tuwien.ac.at





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